

## TWO-CYCLIC TRIANGULAR SKEW-SYMMETRIC ITERATION METHOD FOR SOLVING STRONGLY NONSYMMETRIC SYSTEMS

L.A. Krukiyer and L.G. Chikina

*Introduction.* In this article we suggest a new iteration method which allows to solve effectively strongly nonsymmetric systems of equations, which are a result, for example, of a central-difference approximation of the convection–diffusion equation with prevailing convection. Sufficient conditions for convergence are given.

As is known (see [1]), the iteration methods applied for solving the linear systems

$$Ay = f, \tag{1}$$

can be joined by the common formula

$$B_j \frac{y^{j+1} - y^j}{\tau_j} = -(Ay^j - f), \tag{2}$$

where  $\{B_j\}$  is a sequence of nondegenerate matrices,  $\{\tau_j\}$  a sequence of real parameters,  $y^j$  an approximate solution on  $j$ -th iteration. If we introduce the notation  $H_j = \tau_j B_j^{-1}$ , then the iteration process can be written in an equivalent form

$$y^{j+1} = y^j - H_j(Ay^j - f).$$

**Definition** (see [2]). Iterative methods possessing the property  $H_j = H_{j+s}$  for any  $j \geq 0$  and a certain fixed  $s \geq 1$  are said to be cyclic.

Any matrix  $A$  is decomposable into the sum

$$A = A_0 + A_1,$$

where  $A_0 = \frac{1}{2}(A + A^*) = A_0^*$  is the symmetric and  $A_1 = \frac{1}{2}(A - A^*) = -A_1^*$  is skew-symmetric components of the matrix  $A$ . Any skew-symmetric matrix  $A_1$  can be represented as follows

$$A_1 = K_H + K_B,$$

where  $K_H$  and  $K_B$  are the strictly lower and strictly upper triangular parts of the matrix  $A_1$ , respectively, and for them the equalities are valid  $K_H = -K_B^*$ ,  $K_B = -K_H^*$ .

The idea proposed in [3] to include into the operator of the method  $B$  the triangular parts of the skew-symmetric component  $A_1$  of the initial matrix  $A$  allows us to obtain a new class of implicit triangular skew-symmetric iteration methods, which are simultaneously of rather simple structure and are designed for solving systems with nonselfadjoint strongly nonsymmetric<sup>1</sup> matrices.

In [3], a structure of the operator  $B$  was suggested satisfying the equality

$$B_1 = \tau A_1, \tag{3}$$

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<sup>1</sup> A matrix  $A$  is said to be *strongly nonsymmetric* if an a certain norm  $\|A_1\| \gg \|A_0\|$ .

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