

CHARACTERISTIC PRINCIPLE OF LOCAL EXTREMUM FOR A HYPERBOLIC EQUATION AND ITS APPLICATION

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1. The Goursat problem

Let us consider the equation

$$u_{xy} + \frac{\alpha}{x+y}u_y = 0, \quad 0 < \alpha < 1, \quad (1.1)$$

on the set $G = G_- \cup G_+$, where

$$G_- = \{(x, y) \mid -h < x < 0, -x < y < h\}, \quad G_+ = \{(x, y) \mid 0 < x < h, 0 < y < h - x\}.$$

In a way similar to that in [1] (pp.67–68), in this article, applying the Riemann method for equation (1.1) in the domains G_- and G_+ , we prove the following propositions.

Theorem 1. *If*

$$u(x, h) = \omega(x) \in C_{[-h;0]} \cap C_{(-h;0)}^1, \quad (1.2)$$

$$u(0, y) = \varphi(y) \in C_{[0;h]}^1, \quad (1.3)$$

$\omega(0) = \varphi(h) = 0$, then the Goursat problem in the domain G_- for equation (1.1) with data (1.2), (1.3) has the unique solution

$$u(x, y) = \omega(x) - \int_y^h \varphi'(s)s^\alpha(x+s)^{-\alpha}ds; \quad (1.4)$$

in addition, $u(x, y) \in C(\overline{G_-})$.

Theorem 2. *If*

$$u(x, 0) = \psi(x) \in C_{[0;h]} \cap C_{(0;h)}^1, \quad (1.5)$$

$\psi(0) = \varphi(0) = 0$, then the Goursat problem in the domain G_+ for equation (1.1) with data (1.3), (1.5) has the unique solution

$$u(x, y) = \psi(x) - \int_0^y \varphi'(s)s^\alpha(x+s)^{-\alpha}ds; \quad (1.6)$$

in addition, $u(x, y) \in C(\overline{G_+})$.

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2. Characteristic principle of local extremum

Let

$$v_-(x, y) = \frac{\partial}{\partial x} \int_{-y}^x (x-t)^{-\lambda_1} (-t)^{r_1} u(t, y) dt,$$

where $0 < \lambda_1 < 1$, $\lambda_1 < r_1$, the function $u(t, y)$ be defined by formula (1.4).

Lemma 1. *If the function $u(x, y) \in C(\overline{G_-})$ is such that $u(0, y) = \varphi(y)$ attains its most positive (least negative) value at the point ξ , $0 < \xi < h$, and $u(x, h) \equiv 0$, where $u(x, h)$ is defined by formula (1.2), then $\lim_{x \rightarrow 0-0} v_-(x, \xi) < 0$ (> 0).*

Proof. Using formula (1.4), we find

$$v_-(x, y) = \frac{\partial}{\partial x} \left[\int_{-y}^x \omega(t) (x-t)^{-\lambda_1} (-t)^{r_1} dt - \int_{-y}^x (x-t)^{-\lambda_1} (-t)^{r_1} dt \int_y^h \varphi'(s) s^\alpha (t+s)^{-\alpha} ds \right]. \quad (2.1)$$

We integrate by parts the first addend of the expression standing in the brackets, assuming $U = \omega(t)$,

$$V = V(x, t) = \int_t^x (x-s)^{-\lambda_1} s^{r_1} ds. \quad (2.2)$$

In the second expression in the brackets of equality (2.1) we change the order of integration. We obtain

$$\int_{-y}^x (x-t)^{-\lambda_1} (-t)^{r_1} dt \int_y^h \varphi'(s) s^\alpha (t+s)^{-\alpha} ds = \int_y^h \varphi'(s) s^\alpha ds \int_{-y}^x (x-t)^{-\lambda_1} (-t)^{r_1} (t+s)^{-\alpha} dt. \quad (2.3)$$

Integral (2.2) and the interior integral in the right-hand side of formula (2.3) is calculated by means of the changes of variables $s = t + (x-t)z$ and $t = -y + (x+y)z$, respectively. The results of calculation give us

$$V(x, t) = -\frac{1}{1-\lambda_1} (x-t)^{1-\lambda_1} (-t)^{r_1} F\left(1, -r_1; 2-\lambda_1; \frac{x-t}{-t}\right), \quad (2.4)$$

$$\begin{aligned} & \int_{-y}^x (x-t)^{-\lambda_1} (-t)^{r_1} (t+s)^{-\alpha} dt = \\ & = \frac{1}{1-\lambda_1} y^{r_1} (x+y)^{1-\lambda_1} (s-y)^{-\alpha} F_1\left(1, -r_1, \alpha; 2-\lambda_1; \frac{x+y}{y}, \frac{x+y}{y-s}\right). \end{aligned} \quad (2.5)$$

From equalities (2.2)–(2.5) we determine

$$\begin{aligned} v_-(x, y) = & \frac{\partial}{\partial x} \left[\frac{1}{1-\lambda_1} \omega(-y) (x+y)^{1-\lambda_1} y^{r_1} F\left(1, -r_1; 2-\lambda_1; \frac{x+y}{y}\right) + \right. \\ & + \frac{1}{1-\lambda_1} \int_{-y}^x \omega'(t) (-t)^{r_1} (x-t)^{1-\lambda_1} F\left(1, -r_1; 2-\lambda_1; \frac{x-t}{-t}\right) dt - \\ & \left. - \frac{1}{1-\lambda_1} (x+y)^{1-\lambda_1} y^{r_1} \int_y^h \varphi'(s) s^\alpha (s-y)^{-\alpha} F_1\left(1, -r_1, \alpha; 2-\lambda_1; \frac{x+y}{y}, \frac{x+y}{y-s}\right) ds \right]. \end{aligned}$$

Applying formulas of “quick” differentiation

$$\begin{aligned} \frac{d}{dz} z^{c-1} F(a, b; c; pz) &= (c-1) z^{c-2} F(a, b; c-1; pz), \\ \frac{d}{dz} z^{c-1} F_1(a, b, b'; c; pz, qz) &= (c-1) z^{c-2} F_1(a, b, b'; c-1; pz, qz), \end{aligned}$$

where p and q do not depend on z , proved by V.F. Volkodavov, and the identities (see [2], pp. 73, 232)

$$F(a, b; c; 1) = \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)},$$

$$F_1(a, b, b'; c; 1; z) = \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)}F(a, b'; c-b; z), \quad c-a-b > 0,$$

we find

$$\lim_{x \rightarrow 0-0} v_-(x, y) = \frac{\lambda_1}{r_1 - \lambda_1} \left[y^{r_1 - \lambda_1} \int_y^h \varphi'(s) F\left(r_1 - \lambda_1, \alpha; r_1 - \lambda_1 + 1; \frac{y}{s}\right) ds - \omega(-y)y^{r_1 - \lambda_1} - \int_{-y}^0 \omega'(t)(-t)^{r_1 - \lambda_1} dt \right]. \quad (2.6)$$

By the condition of Lemma

$$\lim_{x \rightarrow 0-0} v_-(x, y) = \frac{\lambda_1}{r_1 - \lambda_1} y^{r_1 - \lambda_1} \int_y^h \varphi'(s) F\left(r_1 - \lambda_1, \alpha; r_1 - \lambda_1 + 1; \frac{y}{s}\right) ds. \quad (2.7)$$

Let $\varphi(y)$ attain the most positive (the least negative value) value at a point ξ , $0 < \xi < h$. Using the identity $(\varphi(t) - \varphi(\xi))' = \varphi'(t)$, in equality (2.7) we integrate by parts, assuming $U = F(r_1 - \lambda_1, \alpha; r_1 - \lambda_1 + 1; \frac{y}{s})$. We obtain

$$\lim_{x \rightarrow 0-0} v_-(x, \xi) = -\frac{\lambda_1}{r_1 - \lambda_1} \xi^{r_1 - \lambda_1} \varphi(\xi) F\left(r_1 - \lambda_1, \alpha; r_1 - \lambda_1 + 1; \frac{\xi}{h}\right) + \frac{\alpha \lambda_1}{r_1 - \lambda_1 + 1} \xi^{r_1 - \lambda_1 + 1} \int_{\xi}^h (\varphi(s) - \varphi(\xi)) s^{-2} F\left(r_1 - \lambda_1 + 1, \alpha + 1; r_1 - \lambda_1 + 2; \frac{\xi}{s}\right) ds.$$

This equality implies the assertions of Lemma.

Let

$$v_+(x, y) = \frac{\partial}{\partial x} \int_x^{h-y} (t-x)^{-\lambda_2} t^{r_2} u(t, y) dt,$$

where $0 < \lambda_2 < 1$, $\lambda_2 < r_2$, the function $u(t, y)$ be defined by formula (1.6). Following the way in the proof of Lemma 1 to obtain expression (2.6), we find

$$\lim_{x \rightarrow 0+0} v_+(x, y) = \frac{\lambda_2}{r_2 - \lambda_2} \left[(h-y)^{r_2 - \lambda_2} \int_0^y \varphi'(s) s^\alpha (s+h-y)^{-\alpha} F\left(1, \alpha; r_2 - \lambda_2 + 1; \frac{h-y}{s+h-y}\right) ds + \psi(h-y)(h-y)^{r_2 - \lambda_2} - \int_0^{h-y} \psi'(t) t^{r_2 - \lambda_2} dt \right]. \quad (2.8)$$

With the use of equality (2.8) as in Lemma 1 we can prove

Lemma 2. *If $u(x, y) \in C(\overline{G}_+)$ is such that $u(0, y) = \varphi(y)$ attains the most positive (the least negative) value at a point ξ , $0 < \xi < h$, and $u(x, 0) \equiv 0$, where $u(x, 0)$ is defined by formula (1.5), $r_2 - \lambda_2 > \alpha$, then $\lim_{x \rightarrow 0+0} v_+(x, \xi) > 0$ (< 0).*

3. The uniqueness and existence of a solution of the problem Δ_2 for equation (1.1)

Problem Δ_2 . On the set G find a solution $u(x, y) \in C(\overline{G}_+ \cap \overline{G}_-)$ of equation (1.1), which satisfies conditions (1.3), (1.4) and the condition of conjugation

$$\lim_{x \rightarrow 0-0} v_-(x, y) = b(y) \lim_{x \rightarrow 0+0} v_+(x, y), \tag{3.1}$$

where $b(y)$ is a given function, $\lim_{x \rightarrow 0-0} v_-(x, y)$ and $\lim_{x \rightarrow 0+0} v_+(x, y)$ are defined by formulas (2.6) and (2.8), respectively.

Theorem 3. *If $b(y) \in C_{(0;h)}$, $b(y) > 0$, $r_2 - \lambda_2 > \alpha$ and a solution of problem Δ_2 exists, then it is unique.*

The proof of this theorem is carried out by the method of proof by contradiction with the use of Lemmas 1 and 2.

Theorem 4. *If the function $\omega(x)$ is subordinated to the condition of Theorem 1, $\psi(x) \in C^1_{[0;h]}$, $\psi(h) = 0$, $r_i - \lambda_i - \alpha > 1$, $i = 1, 2$, $b(y) \equiv b$ ($b > 0$, b is constant), then the unique solution of problem Δ_2 exists.*

Proof. Taking into account formulas (2.6), (2.8) and the condition of conjugacy (3.1), we arrive at the equation with respect to the unknown function $\varphi'(y)$

$$\begin{aligned} & \frac{\lambda_1}{r_1 - \lambda_1} y^{r_1 - \lambda_1} \int_y^h \varphi'(s) F\left(r_1 - \lambda_1, \alpha; r_1 - \lambda_1 + 1; \frac{y}{s}\right) ds - \\ & - \frac{\lambda_2 b}{r_2 - \lambda_2} (h - y)^{r_2 - \lambda_2} \int_0^y \varphi'(s) s^\alpha (s + h - y)^{-\alpha} F\left(1, \alpha; r_2 - \lambda_2 + 1; \frac{h - y}{s + h - y}\right) ds = g(y), \tag{3.2} \\ & g(y) = \frac{\lambda_1}{r_1 - \lambda_2} \omega(-y) y^{r_1 - \lambda_1} + \frac{\lambda_1}{r_1 - \lambda_1} \int_{-y}^0 \omega'(t) (-t)^{r_1 - \lambda_1} dt + \\ & + \frac{b \lambda_2}{r_2 - \lambda_2} \psi(h - y) (h - y)^{r_2 - \lambda_2} - \frac{b \lambda_2}{r_2 - \lambda_2} \int_0^{h - y} \psi'(t) t^{r_2 - \lambda_2} dt. \end{aligned}$$

Let $\varphi'(t)$ be a solution of equation (3.2). Under the fulfillment of the conditions of Theorem we differentiate both the sides of this identity with respect to y , applying here the identity (see [2], p. 111)

$$\frac{d}{dz} z^{c-1} (1 - z)^{b-c+1} F(a, b; c; z) = (c - 1) z^{c-2} (1 - z)^{b-c} F(a - 1, b; c - 1; z).$$

The differentiation of identity (3.2) leads us to the equation

$$\varphi'(y) = \int_0^h \varphi'(s) K(y, s) ds + f(y), \tag{3.3}$$

$$K(y, s) = \begin{cases} K_1(y, s), & 0 \leq s \leq y; \\ K_2(y, s), & y \leq s \leq h, \end{cases}$$

$$K_1(y, s) = -\frac{b \lambda_2}{a(y)} (h - y)^{r_2 - \lambda_2 - 1} y^{-\alpha} s^\alpha (s + h - y)^{-\alpha}, \quad K_2(y, s) = -\frac{\lambda_1}{a(y)} y^{r_1 - \lambda_1 - \alpha - 1} (s - y)^\alpha s^{-\alpha},$$

$$a(y) = -\lambda_1 B(r_1 - \lambda_1; 1 - \alpha) y^{r_1 - \lambda_1 - \alpha} - \frac{b \lambda_2}{r_2 - \lambda_2} h^{-\alpha} (h - y)^{r_2 - \lambda_2} F\left(1, \alpha; r_2 - \lambda_2 + 1; \frac{h - y}{h}\right),$$

$$f(y) = -\frac{1}{a(y)} y^{-\alpha} [\lambda_1 \omega(-y) y^{r_1 - \lambda_1 - 1} - b \lambda_2 \psi(h - y) (h - y)^{r_2 - \lambda_2 - 1}].$$

Under the fulfillment of the conditions of this theorem $a(y), f(y) \in C_{[0;h]}$, and $a(y) < 0$, $y \in [0; h]$. One can easily see that $K(y, s)$ is a bounded function in $[0, h; 0, h]$ and possesses one line of a finite

discontinuity, i. e., by the definition it is a regular kernel (see [3], p. 19). In [3] (pp. 39–55) the existence and uniqueness of a solution of equation (3.3) were proved. This solution can be written via the resolvent

$$\varphi'(y) = f(y) + \int_0^h R(y, s; 1)f(s)ds,$$

which is not cited here in view of its cumbersome form (see [3], p. 54).

The existence and uniqueness of the solution of equation (3.3) imply the existence of the solution of Problem Δ_2 . Theorem 4 has been proved.

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