

Computational Tricks in Linear Programming Without the Use of Artificial Variables

Ya. I. Zabotin¹

¹Kazan State University, ul. Kremlyovskaya 18, Kazan, 420008 Russia¹

Received February 14, 2007

DOI: 10.3103/S1066369X08010039

We describe two computational tricks without the use of artificial variables, concerning the solution of the problem

$$c^T x - \min, \quad Ax = P_0, \quad x \geq 0, \quad (1)$$

where $c = (c_1, c_2, \dots, c_n)^T$, $x = (\xi_1, \xi_2, \dots, \xi_n)^T$, A is a matrix of the dimension $m \times n$ with the rank m . Assume that $m < n$. We denote columns of the matrix A by P_j , $j = 1, \dots, n$. If P_1, P_2, \dots, P_m is a basis in R_m , then we say that a submatrix $B = (P_1, P_2, \dots, P_m)$ of the matrix A is a basis matrix and treat the collection of vectors P_1, P_2, \dots, P_m as a basis B . Denote $c_B = (c_1, c_2, \dots, c_m)^T$, $\Delta_j = c_B^T B^{-1} P_j - c_j$, $j = 0, 1, \dots, n$, $c_0 = 0$. As usual, we understand the inequality $x \geq 0$ as the condition $\xi_j \geq 0$ for all $j = 1, \dots, n$. We also use the standard definitions of [1], [2].

One can easily verify that the vector $B^{-1} P_j$ represents a collection of expansion coefficients of the vector P_j in the basis B . Components of the vector $B^{-1} P_j$ are said to be basis coordinates of the vector P_j . Note that the equality $Ax = P_0$ admits the form

$$\sum_{j=1}^n \xi_j P_j = P_0, \quad (2)$$

and the main part of the simplex table represents the extended matrix of the system of linear algebraic equations

$$\sum_{j=1}^n \xi_j B^{-1} P_j = B^{-1} P_0, \quad (3)$$

which is equivalent to system (2). In other words, columns of any simplex table which corresponds to a certain basis B represent collections of expansion coefficients of vectors P_j in this basis.

It is well-known (e.g., [1], P. 37) that if a basis matrix B concurrently satisfies the conditions

$$B^{-1} P_0 \geq 0 \quad (4)$$

and

$$\Delta_j \leq 0 \quad \forall j = 1, \dots, n, \quad (5)$$

then problem (1) is solved, because coordinates of the vector $B^{-1} P_0$ are basis coordinates of the optimal plan of problem (1), and Δ_0 is the optimal value of the linear form $c^T x$. If a basis B is such that condition (4) is true and (5) is false, then we solve problem (1) by the simplex method. But if condition (5) is true and (4) is false, then we use the dual simplex method.

With an arbitrary initial basis B usually neither condition (4) nor (5) is fulfilled. For such a case in this paper we propose two solution algorithms for problem (1); they use the simplex and dual simplex methods sequentially.

¹E-mail: Yaroslav.Zabotin@ksu.ru.