

The Berger–Ebin Theorem and Harmonic Maps and Flows

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Abstract—The purpose of this paper is to present a geometrization of the Berger–Ebin theorem. We use this theorem for the study of harmonic maps and flows, in particular, Ricci solitons. We also clarify the role of a vector field in the corresponding decompositions.

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1. INTRODUCTION

1.1. The Berger–Ebin theorem [1] is a classical result in the Riemannian geometry in the large and is included in monographs (see, e.g., [2]). By this theorem, an arbitrary symmetric 2-form φ on a closed oriented Riemannian manifold can be represented as the orthogonal sum $\varphi = \varphi^0 + \varphi^1$ of a divergence-free symmetric 2-form φ^0 and a symmetric 2-form $\varphi^1 := L_X g$, where L_X is the Lie derivative with respect to a vector field X .

In this paper, we use the Berger–Ebin decomposition for the study of harmonic maps and flows, in particular, Ricci solitons. We also clarify the role of the vector field X in the corresponding decompositions.

2. THE BERGER–EBIN DECOMPOSITION

2.1. Let (M, g) be a C^∞ Riemannian manifold of dimension $n \geq 2$, and let ∇ denote the Levi-Civita connection of (M, g) . Let TM denote the tangent bundle of M , T^*M the cotangent bundle, and $S^p M$ the bundle of symmetric p -forms on M . The metrics on the fibers of these bundles are determined by the Riemannian structure g on M . Denote by $C^\infty TM$, $C^\infty T^*M$, and $C^\infty S^p M$ the spaces of C^∞ -sections of the above listed bundles respectively. These spaces possess natural scalar products $\langle \cdot, \cdot \rangle$. In particular ([3], Chap. 4, § 1), we have $\langle \varphi, \varphi' \rangle := \int_M \frac{1}{p!} g(\varphi, \varphi') dv$ for arbitrary $\varphi, \varphi' \in C^\infty S^p M$.

Define a differential operator $\delta^* : C^\infty S^p M \rightarrow C^\infty S^{p+1} M$ by the relation

$$(\delta^* \varphi)_{i_0 i_1 \dots i_{p-1} i_p} = \nabla_{i_0} \varphi_{i_1 \dots i_{p-1} i_p} + \dots + \nabla_{i_p} \varphi_{i_0 i_1 \dots i_{p-1}}$$

for the local components $\varphi_{i_1 \dots i_p}$ of an arbitrary form $\varphi \in C^\infty S^p M$ and the covariant differentiation ∇_j with respect the vector fields $X_j = \frac{\partial}{\partial x^j}$ in terms of local coordinates x^1, x^2, \dots, x^n on M . In particular, for an arbitrary 1-form ω and a vector field $X := \omega^\#$ dual to the 1-form ω with respect to g , we have $\delta^* \omega = L_X g$, where L_X denotes the Lie derivative with respect to a vector field X ([1]; [2], pp. 54–55). In the classical tensor notation, the symbol $\#$ corresponds to the raising of an index ([2], P. 47). In particular, $\delta^* \omega = 0$ if and only if $L_X g = 0$. In this case, the local one-parameter group generated by X consists of local isometries, and X is a *Killing vector field* ([2], P. 61).

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