

Review

Gravity with Higher Derivatives in D-Dimensions

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Abstract: The aim of this review is to discuss the ways to obtain results based on gravity with higher derivatives in D-dimensional world. We considered the following ways: (1) reduction to scalar tensor gravity, (2) direct solution of the equations of motion, (3) derivation of approximate equations in the presence of a small parameter in the system, and (4) the method of test functions. Some applications are presented to illustrate each method. The unification of two necessary elements of a future theory is also kept in mind—the extra dimensions and the extended form of the gravity.

Keywords: multidimensional gravity; compact extra dimensions; gravity with higher derivatives; cosmology

1. Introduction

Higher derivative theories of gravity is widely used in modern research despite the internal problems inherent in this approach [1,2]. One such problem is the Ostrogradsky instabilities [3]. The $f(R)$ -gravity is the simplest extension of the Einstein–Hilbert theory of gravity, which is free from Ostrogradsky instabilities. Reviews of $f(R)$ —theories, including extension to the Gauss–Bonnet gravity, can be found in [4,5]. The specific form of the function $f(R)$ was considered in [6–8].

Another widespread idea, the world with extra dimensions is considered as the necessary element for a complete fundamental theory. The idea of extra dimensions is also used to explain cosmological evolution [9]. The invisibility of extra dimensions can be explained by their small size smaller than 10^{-18} cm.

One of the aims of our research is to combine two main elements of future theory—the gravity with higher derivatives and the extra dimensions. The latter could reveal itself at the inflationary energies and higher.

It is generally assumed that our Universe was born at Planck energies and evolved by expanding and cooling to its present state. The inflationary stage is characterized by sub-Planckian energy density and looks inevitable. A description of the spontaneous creation of the Universe with the inflationary regime can be found in [10]. Models describing the inflation have been elaborated using many different ingredients, like supersymmetry [11] and attracting the inflationary idea for explanation of another cosmological problems like primordial black holes [12,13], dark matter [14], and baryogenesis [15]. For review, see, for example, [16,17] and references therein. Since the energy scale at the inflationary stage of the evolution of the Universe is high enough, some quantum effects may be manifested and responsible for the inflationary regime. Two typical elements of quantum gravity can play a role in the construction of inflationary models: nonlinear geometrical extensions of Einstein’s theory of gravity and extra dimensions. Moreover, the quantization of gravity requires a nonlinear geometric extension of the Einstein–Hilbert action. The first formulation of the inflationary model, the Starobinsky model [18], considers nonlinear geometric terms belonging to the class of $f(R)$ theories.

To our knowledge, there are four ways to move forward in the framework of higher derivative theories of gravity in D-dimensions:

1. Reduction of action to the scalar tensor gravity. This way is effective for the action in the form

$$S = \frac{m_D^{D-2}}{2} \int d^D Z \sqrt{|g_D|} f(R). \quad (1)$$

2. Direct solution to equations of motion.
3. Derivation of approximate equations provided that a system contains a small parameter.
4. Method of trial functions.

The next sections are devoted to their discussion.

Throughout this paper, we use the following conventions: $R_{ABC}^D = \partial_C \Gamma_{AB}^D - \partial_B \Gamma_{AC}^D + \Gamma_{EC}^D \Gamma_{BA}^E - \Gamma_{EB}^D \Gamma_{AC}^E$, $R_{MN} = R_{MFN}^F$.

2. Reduction of Action to the Scalar-Tensor Gravity

$f(R)$ theories of gravity or, more generally, higher derivative theories of gravity are now widely used as a tool for theoretical research. The interest in $f(R)$ theories is motivated by inflationary scenarios of the evolution of the Universe, starting with Starobinsky's pioneering work [18]. A number of viable $f(R)$ models in four-dimensional space-time satisfying the observable constraints are discussed in [19–21].

The first method is based mostly on the conformal transformations that lead to the standard form of Einstein's gravitational action. The price is the appearance of the additional dynamic variable in the form of the scalar field. Necessary formulas for the D-dim space are represented in the section below.

2.1. Conformal Transformations in D Dimensions

Action (1) can be reduced to a scalar-tensor model in two steps. Firstly, consider the action depending on auxiliary scalar field χ

$$S_{ST} = \frac{m_D^{D-2}}{2} \int d^D Z \sqrt{|g_D|} [f'(\chi)R + f(\chi) - f'(\chi)\chi] \quad (2)$$

One of the classical equation is

$$f''(\chi)(R - \chi) = 0 \quad (3)$$

Thus, $\chi = R$ provided that $f''(\chi) \neq 0$. Substituting this into (2), we arrive to initial action (1). These actions are equivalent at the classical level.

As the second step is based on the well known conformal transformation, see e.g., [22]

$$g_{AB} = |\Omega|^{\frac{-2}{D-2}} \hat{g}_{AB}, \quad (4)$$

which leads to the Ricci scalar transformation in the form

$$\sqrt{g_D} \Omega R = (\text{sign } \Omega) \sqrt{\hat{g}_D} \left[\hat{R} + \frac{D-1}{D-2} \frac{\partial_A \Omega \hat{g}^{AB} \partial_B \Omega}{\Omega^2} \right] + \text{div}. \quad (5)$$

Here, all letters with hat are functions of \hat{g}_{AB} , and div denotes a full divergence which does not contribute to the field equations.

Application of the conformal transformation (4) with $\Omega = f'$ to expression (2) gives

$$S = \frac{1}{2} \int d^D x \sqrt{|\hat{g}_D|} [\hat{R} + (\partial\psi)^2 - 2V(\psi)] \quad (6)$$

where

$$\psi = \sqrt{\frac{D-2}{D-1}} \ln f'(\chi) \quad (7)$$

$(m_D = 1)$ and

$$V(\psi) = e^{\frac{-D}{\sqrt{(D-1)(D-2)}}\psi} U(\chi), \quad U(\chi) \equiv \frac{1}{2}(f'(\chi)\chi - f(\chi)). \quad (8)$$

The Lagrangian containing the Ricci scalar in the form of specific function $f(R)$ is transformed into the scalar-tensor model that strongly simplifies the subsequent calculations. The applications are wide and can be found in a set of publications [4,19–21,23]. Here, we consider one of the applications concerning the Starobinsky model of inflation [18].

2.2. The Starobinsky Model

This model provides the best fit to the observational data at present times. Historically, this was the first model of inflation, but many models containing the scalar field(s) were intensively discussed during a couple of decades. These models are well elaborated and intuitively clear.

The model in question is described by the action (1) with $D = 4$ and $f(R) = R + R^2/6M^2$. As one can see from the previous section, the conformal transformation leads to the scalar-tensor model of inflation, allowing the application of already known results [24]. Indeed, action (2) is the starting point for the inflationary models based on a scalar field dynamic. According to (8), the potential has the form

$$V(\psi) = \frac{3}{4}m_4^2 M^2 \left(1 - e^{-\sqrt{2/3}\psi/m_4}\right)^2 \quad (9)$$

We have obtained an effective model containing the Einstein–Hilbert action and the scalar field in the standard form. The scalar field potential possesses a profound minimum at $\psi = 0$. The latter is a necessary element responsible for the field oscillations and hence the reheating just after the end of inflation. The ground state energy should also be zero with great accuracy due to the extreme smallness of the cosmological constant.

A variety of inflationary models that differ in the form of the potential are described by action (6). Most of them are based on the slow motion of fields and should satisfy some conditions which characterized the inflationary stage. The slow roll parameters are defined as

$$\epsilon = \frac{1}{2} \left(\frac{V'}{V} \right)^2, \quad (10)$$

$$\eta = \frac{V''}{V}, \quad (11)$$

$$\xi^2 = \frac{V'V'''}{V^2}. \quad (12)$$

The main parameters are the scalar/tensorial relative amplitude r and the scalar spectral index n_s , besides the running of the spectral index $dn_s/d \ln k$, which are given, in terms of the slow roll parameters, as

$$n_s = 1 - 6\epsilon + 2\eta, \quad (13)$$

$$r = 16\epsilon, \quad (14)$$

$$\frac{dn_s}{d \ln k} = -16\epsilon\eta + 24\epsilon^2 + 2\xi^2. \quad (15)$$

k is the wavenumber.

According to [16], the observed values are as follows:

$$n_s \simeq 0.968, \quad r < 0.1, \quad \frac{dn_s}{d \ln k} = -0.0045 \pm 0.0067. \quad (16)$$

The potential (9) satisfies all of them for $M \simeq 10^{-5}$. Notice that this potential has only one parameter, M , and nevertheless gives the best fit to the observations.

We see that the method of conformal transformations allows us to apply the well-known results elaborated for the scalar fields, thus making the physical picture clearer. The known flaws of this approach are (a) quantum correspondence before and after the conformal transformations is suspicious, (b) treating more general forms of Lagrangian is not easy.

Let us discuss the second way—numerical solution to the proper system of equations.

3. Direct Solution to Equations of Motion

We will illustrate this way for two cases:

- $f(R)$ gravity,
- $f(R) + \text{Gauss–Bonnet}$ gravity.

3.1. $f(R)$ Gravity

Let a $D = 1 + d_1 + d_2$ -dimensional space-time $T \times M_{d_1} \times M_{d_2}$ appeared as a result of some quantum processes at high energies. The probability of these processes is a subtle point, and we do not discuss it in this article. It is supposed that manifolds are born with a random shape. The entropy growth in $T \times M_{d_1} \times M_{d_2}$ manifold leads to the entropy minimization of subspace M_{d_2} [25]. We begin our research after completing symmetrization and investigate the classical evolution of subspaces M_{d_1} and M_{d_2} whose metric

$$ds^2 = dt^2 - e^{2\beta_1(t)} d\Omega_1^2 - e^{2\beta_2(t)} d\Omega_2^2 \quad (17)$$

is assumed to be maximally symmetrical with a positive curvature. In this section, we consider the action in the form (1). The equations of this theory are known,

$$-\frac{1}{2}f(R)\delta_A^B + \left(R_A^B + \nabla_A \nabla^B - \delta_A^B \square\right)f_R = 0. \quad (18)$$

The nontrivial equations of system (18) are

$$\begin{aligned} & -\frac{1}{2}f(R) + f_R \left[e^{-2\beta_1(t)}(d_1 - 1) + \ddot{\beta}_1 + \dot{\beta}_1(d_1\dot{\beta}_1 + d_2\dot{\beta}_2) \right] \\ & + \left[(1 - d_1)\dot{\beta}_1 - d_2\dot{\beta}_2 \right] f_{RR}\dot{R} - f_{RRR}\dot{R}^2 - f_{RR}\ddot{R} = 0, \end{aligned} \quad (19)$$

$$\begin{aligned} & -\frac{1}{2}f(R) + f_R \left[e^{-2\beta_2(t)}(d_2 - 1) + \ddot{\beta}_2 + \dot{\beta}_2(d_1\dot{\beta}_1 + d_2\dot{\beta}_2) \right] \\ & + \left[(1 - d_2)\dot{\beta}_2 - d_1\dot{\beta}_1 \right] f_{RR}\dot{R} - f_{RRR}\dot{R}^2 - f_{RR}\ddot{R} = 0, \end{aligned} \quad (20)$$

$$-\frac{1}{2}f(R) + \left[d_1\ddot{\beta}_1 + d_2\ddot{\beta}_2 + d_1\dot{\beta}_1^2 + d_2\dot{\beta}_2^2 \right] f_R - (d_1\dot{\beta}_1 + d_2\dot{\beta}_2) f_{RR}\dot{R} = 0 \quad (21)$$

in terms of metric (17). Here, we took into account that $\partial_t f_R = f_{RR}\dot{R}$ and $\partial_t^2 f_R = f_{RRR}\dot{R}^2 + f_{RR}\ddot{R}$. The Ricci scalar is

$$\begin{aligned} R = & d_1\ddot{\beta}_1 + d_2\ddot{\beta}_2 + d_1\dot{\beta}_1^2 + d_2\dot{\beta}_2^2 + d_1 \left[e^{-2\beta_1(t)}(d_1 - 1) + \ddot{\beta}_1 \right. \\ & \left. + \dot{\beta}_1(d_1\dot{\beta}_1 + d_2\dot{\beta}_2) \right] + d_2 \left[e^{-2\beta_2(t)}(d_2 - 1) + \ddot{\beta}_2 + \dot{\beta}_2(d_1\dot{\beta}_1 + d_2\dot{\beta}_2) \right]. \end{aligned} \quad (22)$$

The system of Equations (19)–(21) is a system of fourth-order differential equations with respect to unknown functions $\beta_1(t)$ and $\beta_2(t)$. Note that this system is not solvable with respect to the highest derivatives $\ddot{\beta}_1$ and $\ddot{\beta}_2$ because these derivatives appear when expression (22) is substituted into the

similar terms $-f_{RR}\ddot{R}$ of Equations (19) and (20). Therefore, two equations contain the forth-order derivatives with equal multipliers.

Another way to solve the problem is as follows: we can consider $R(t)$ as an additional unknown function, and the expression (22) as the fourth equation of the system. In this case, we obtain a system of second order ordinary differential equations for the unknown functions $\beta_1(t)$, $\beta_2(t)$, and $R(t)$. Three equations of this system (for example, (19), (20), (22)) can be solved with respect to $\ddot{\beta}_1$, $\ddot{\beta}_2$, \ddot{R} . Then, substitution $\ddot{\beta}_2$ and $\ddot{\beta}_1$ into Equation (21) gives equation

$$-10 [d_1\dot{\beta}_1 + d_2\dot{\beta}_2] f_{RR}\ddot{R} + [5R - 5d_1(d_1 - 1)\dot{\beta}_1^2 - 10d_1d_2\dot{\beta}_1\dot{\beta}_2 - 5d_2(d_2 - 1)\dot{\beta}_2^2 - 5d_1(d_1 - 1)e^{-2\beta_1} - 5d_2(d_2 - 1)e^{-2\beta_2}] f_R - 5f(R) = 0, \quad (23)$$

which plays the role of restriction for our system of differential equations. Equation (23) should be used to obtain a relation between the initial data $\beta_1(t_0)$, $\dot{\beta}_1(t_0)$, $\beta_2(t_0)$, $\dot{\beta}_2(t_0)$, and $\dot{R}(t_0)$. The value $R(0)$ can be found from auxiliary condition (23) at $t = 0$. Let

$$f(R) = a_3R^3 + a_2R^2 + a_1R + a_0 \quad (24)$$

with the parameter values (the choice is quite arbitrary)

$$a_0 = 0.6, a_1 = 1, a_2 = -2, a_3 = 1.3. \quad (25)$$

Figure 1 shows the numerical solution of the system of Equations (19), (20), and (22) in different time ranges. The region of small values of time is shown at the left panel. The time behavior of both functions $\beta_1(t)$ and $\beta_2(t)$ differ from each other due to differences in the initial conditions, see the capture of Figure 1. The panel in the middle indicates similar asymptotic behavior of the solutions. The more detailed figure on the right panel helps distinguish the functions $\beta_1(t)$ and $\beta_2(t)$.

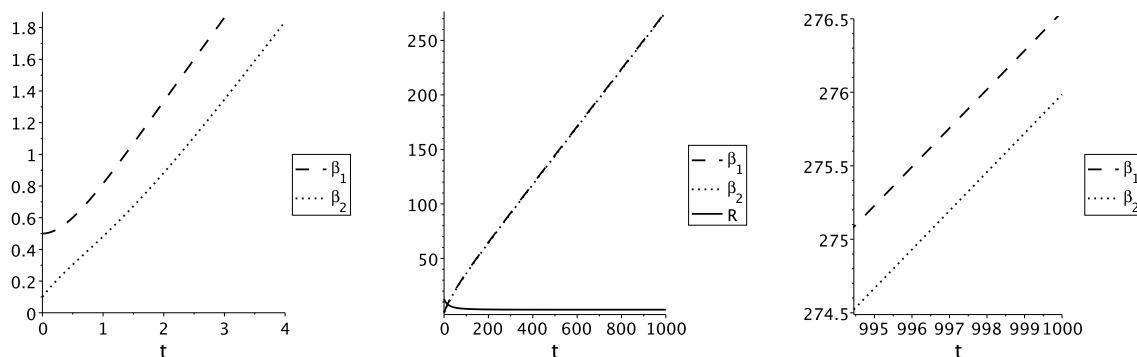


Figure 1. Numerical solution of (19), (20) and (22) for $d_1 = d_2 = 3$, $\beta_1(0) = 0.5$, $\dot{\beta}_1(0) = 0$, $\beta_2(0) = 0.1$, $\dot{\beta}_2(0) = 0.5$, $\dot{R}(0) = 0$. $R(0) \simeq 12.67452$ is found from Equation (23).

The asymptotics of the solution

$$\beta_1(t) = H_1 t, \quad \beta_2(t) = H_2 t \quad (H_1 > 0, H_2 > 0). \quad (26)$$

are determined by the Equations (19)–(22) at $t \rightarrow \infty$

$$R(t) = d_1(d_1 + 1)H_1^2 + d_2(d_2 + 1)H_2^2 + 2d_1d_2H_1H_2 \equiv R_0, \quad (27)$$

$$f_R \left(d_1 H_1^2 + d_2 H_1 H_2 \right) - \frac{1}{2} f \Big|_{R=R_0} = 0, \quad (28)$$

$$f_R \left(d_2 H_2^2 + d_1 H_1 H_2 \right) - \frac{1}{2} f \Big|_{R=R_0} = 0, \quad (28)$$

$$f_R \left(d_1 H_1^2 + d_2 H_2^2 \right) - \frac{1}{2} f \Big|_{R=R_0} = 0. \quad (29)$$

According to these equations, the subspaces are expanded with equal speed,

$$H_1 = H_2 = \sqrt{\frac{f}{2(d_1 + d_2)f_R}} \Big|_{R=R_0}. \quad (30)$$

Using this expression, we obtain the equation for R_0 from (27)

$$-(d_1 + d_2 + 1)f \Big|_{R=R_0} + 2Rf_R \Big|_{R=R_0} = 0. \quad (31)$$

We note that the results at $t \rightarrow \infty$ do not depend on the initial conditions and H_1, H_2, R_0 are consistent with the numerical results. Nevertheless, the conclusion that the asymptotic behavior is independent of the initial conditions in their whole range is hasty. As shown in Figure 2, for some initial conditions, there is no stable solution.

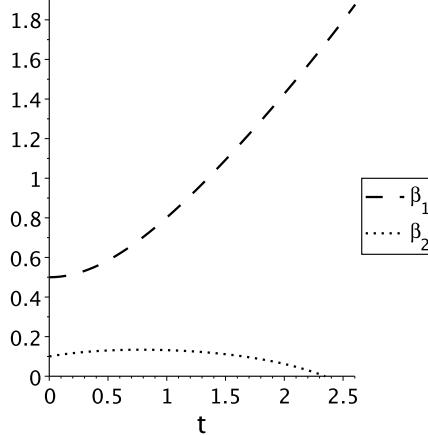


Figure 2. The same as in Figure 1 except $\dot{\beta}_2(0) = 0.1$.

The discussion above indicates that time dependence of an extra space metric is determined by the initial conditions. The latter leads to growing volumes of both extra spaces, which means that such solutions are hardly applicable to the description of our Universe.

In a more realistic situation, the radius of one of the subspaces (say, M_{d_2}) remains constant

$$\beta_2(t) = \beta_c = \text{const}, \quad (32)$$

while the other one, M_{d_1} , expands. In this case, the system of Equations (19)–(22) admits an analytic solution. More definitely, the combination $d_1 \cdot (19) - d_1 \cdot (20) + (21) - f_R \cdot (22)$ gives

$$-\frac{f(R)}{2} + \left[R(t) + \frac{d_1 + d_2 - d_2(d_1 + d_2)}{e^{\beta_c}} \right] f_R = 0. \quad (33)$$

It means that

$$R(t) = R_0 = \text{const} \quad (34)$$

and R_0 can be found from Equation (33). Then, Equations (19)–(22) can be rewritten as

$$R_0 = 2d_1\ddot{\beta}_1 + d_1(d_1 + 1)\dot{\beta}_1^2 + d_1(d_1 - 1)e^{-2\beta_1(t)} + d_2(d_2 - 1)e^{-2\beta_c}, \quad (35)$$

$$-\frac{1}{2}f(R_0) + f_R \left[e^{-2\beta_1(t)}(d_1 - 1) + \ddot{\beta}_1 + d_1\dot{\beta}_1^2 \right] \Big|_{R=R_0} = 0, \quad (36)$$

$$-\frac{1}{2}f(R_0) + e^{-2\beta_c}(d_2 - 1)f_R \Big|_{R=R_0} = 0, \quad (37)$$

$$-\frac{1}{2}f(R_0) + d_1 \left(\ddot{\beta}_1 + \dot{\beta}_1^2 \right) f_R \Big|_{R=R_0} = 0. \quad (38)$$

Subtracting Equation (36) from (38), we obtain

$$(d_1 - 1) \left(\ddot{\beta}_1 - e^{-2\beta_1(t)} \right) f_R \Big|_{R=R_0} = 0, \quad (39)$$

which gives the connection

$$\ddot{\beta}_1 = e^{-2\beta_1(t)} \quad (40)$$

for $d_1 \neq 1$, $f_R|_{R=R_0} \neq 0$. Then, Equations (35)–(38) are reduced to

$$e^{-2\beta_1(t)} + \dot{\beta}_1^2 = \frac{e^{-2\beta_c}(d_2 - 1)}{d_1} = \frac{f(R)}{2d_1 f_R} \Big|_{R=R_0} = \frac{R_0 - d_2(d_2 - 1)e^{-2\beta_c}}{d_1(d_1 + 1)} \equiv H^2. \quad (41)$$

The solution of Equations (41) and (40) with respect to $\beta_1(t)$ is

$$\beta_1(t) = \pm H(t - t_0) + \ln \left(\frac{1 + e^{\mp 2H(t-t_0)}}{2H} \right), \quad H > 0, \quad (42)$$

where H , R_0 and β_c can be found from the last relations (41).

In this section, we have obtained a set of numerical and analytical solutions in $f(R)$ gravity. Dependence on the initial conditions appears to be nontrivial. The relation between the initial conditions and the asymptotes of the solutions is also not clear.

3.2. Starobinsky Model, Direct Calculation

Let us come back to Starobinsky model discussed above and perform the direct simulations. Both approaches should give similar results. To this end, consider the four-dimensional theory described by the action

$$S[g_{\mu\nu}] = \frac{1}{2}m_{Pl}^2 \int d^4x \sqrt{|g_4|} f(R). \quad (43)$$

The corresponding equations of motion in four dimensions are as follows:

$$f'_R(R)R_{\mu\nu} - \frac{1}{2}f(R)g_{\mu\nu} + \left[\nabla_\mu \nabla_\nu - g_{\mu\nu}\square \right] f'_R(R) = 0, \quad \square \equiv g^{\mu\nu}\nabla_\mu \nabla_\nu \quad (44)$$

with $\mu, \nu = 1, 2, 3, 4$. Taking into account the choice of the metric of the three-dimensional sphere

$$ds^2 = g_{\mu\nu}dx^\mu dx^\nu = dt^2 - e^{2\alpha(t)} \left(dx^2 + \sin^2 x dy^2 + \sin^2 x \sin^2 y dz^2 \right) \quad (45)$$

we obtain the system of equations

$$\begin{cases} 6\dot{\alpha}(t)\dot{R}(t)f_R''(R) - 6(\ddot{\alpha}(t) + \dot{\alpha}^2(t))f_R'(R) + f(R) = 0, \\ 2\dot{R}^2(t)f_R'''(R) + 2(\ddot{R}(t) + 2\dot{\alpha}(t)\dot{R}(t))f_R''(R) - (2\ddot{\alpha}(t) + 6\dot{\alpha}^2(t) + 4e^{-2\alpha(t)})f_R'(R) + f(R) = 0, \end{cases} \quad (46)$$

where the definition of the Ricci scalar for metric (45) is

$$R(t) = 12\dot{\alpha}^2(t) + 6\ddot{\alpha}(t) + 6e^{-2\alpha(t)}. \quad (47)$$

Let us choose the form of the function as in the Starobinsky model

$$f(R) = \frac{R^2}{6M^2} + R, \quad (48)$$

where M is a constant parameter with dimension of mass and is defined as

$$M \sim 1.5 \cdot 10^{-5} m_{Pl} \left(\frac{50}{N_e} \right), \quad N_e = 55 \div 60. \quad (49)$$

Using the second equation of the system (46) and the definition of the Ricci scalar (47), we get

$$\begin{cases} \ddot{R}(t) = -2\dot{\alpha}(t)\dot{R}(t) - \frac{1}{12}R^2(t) + (\dot{\alpha}^2(t) + e^{-2\alpha(t)} - M^2)R(t) + 3M^2(\dot{\alpha}^2(t) + e^{-2\alpha(t)}), \\ \ddot{\alpha}(t) = -2\dot{\alpha}^2(t) - e^{-2\alpha(t)} + \frac{1}{6}R(t). \end{cases} \quad (50)$$

The second derivative $\ddot{\alpha}(t)$ is disappeared in a combination of the first equation of the system (46) and definition of the Ricci scalar (47). Finally, we obtain the quadratic equation

$$R^2(t) - 12(\dot{\alpha}^2(t) + e^{-2\alpha(t)})R(t) - 12\dot{\alpha}(t)\dot{R}(t) - 36M^2(\dot{\alpha}^2(t) + e^{-2\alpha(t)}) = 0. \quad (51)$$

This expression being substituted into the first equation of the system (50), leads to the equation of free damped harmonic oscillations

$$\ddot{R}(t) + 3\dot{\alpha}(t)\dot{R}(t) + M^2R(t) = 0. \quad (52)$$

We need to choose the initial conditions to find a solution for the unknown functions $\alpha(t)$ and $R(t)$. Let the initial conditions on the function $\alpha(t)$ in Planck units be given as

$$\alpha(0) \equiv \alpha_0 = -\ln H_{infl} = \ln 10^6 \sim 13.8, \quad \dot{\alpha}(0) \equiv \alpha_1 = H_{infl} \sim 10^{-6}. \quad (53)$$

Solving the previously obtained Equation (51), we find an expression for the function $R(t)$ at the initial time depending on the value of other initial conditions

$$R(0) \equiv R_0 = 6(\alpha_1^2 + e^{-2\alpha_0}) \pm \sqrt{36(\alpha_1^2 + e^{-2\alpha_0})^2 + (12\alpha_1 R_1 + 36M^2(\alpha_1^2 + e^{-2\alpha_0}))}. \quad (54)$$

Thus, after substitution of specific values of quantities, we get

$$\dot{R}(0) \equiv R_1 = 0 \xrightarrow{(54)} R_+(0) = 2.9 \cdot 10^{-11}, \quad R_-(0) = -4.3 \cdot 10^{-12}. \quad (55)$$

The result of numerical solving the system (50) with the choice of the initial conditions (53) and (55) is presented in Figure 3. The time interval of inflation is between 10^{-42} s and 10^{-36} s and is equal on the Planck scale to ~ 20 and $\sim 2 \cdot 10^7$, respectively. The slope of the straight line for the

function $\alpha(t)$ changes at a value of time close to the end of inflation, where oscillations of the curvature $R(t)$ begin. This is shown on the right side of Figure 3. The origin of these oscillations is clear from the Equation (52). When a regime $1.5\dot{\alpha}(t) < M$ occurs in this equation, the solution is damped oscillations. This condition leads to the spacetime being considered flat or of small curvature: at the inflation stage, $R \sim 12H_{Infl}^2 = 12\dot{\alpha}^2(t) \Rightarrow |R| \ll M^2 \sim 10^{-10}$. The size of the space at the inflation stage should increase by $\sim 10^{26}$ times and, for the function $\alpha(t)$, it is a value of about 60; we see that the result shown in Figure 3 confirms this fact. Numerical calculation gives the value of the Hubble constant in Planck units $H_{Infl} \equiv \dot{\alpha}(t) \sim 10^{-6}$ within the required order during inflation.

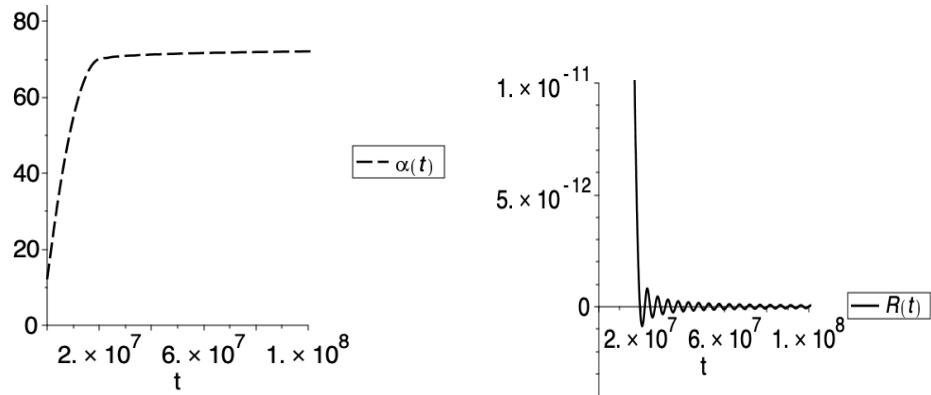


Figure 3. Solution for the system (50) with the initial conditions (53) and (55).

Asymptotic behavior can be found after reconstruction of the numerical solution. The size of the sphere $\sim \exp\{\alpha(t_{Univ})\} \sim \exp\{154\}$, the curvature value $R(t_{Univ}) \sim 10^{-122}$ and the value of the derivative of the function $\dot{\alpha}(t_{Univ}) \sim 10^{-61}$.

As a result, the direct numerical simulation and application of the conformal transformation give similar results and may be used if a Lagrangian is not very complicated.

3.3. $f(R) + \text{Gauss–Bonnet Gravity}$

In this section, we extend our study to action in the more complex form

$$S_{eff} = \frac{1}{2}m_D^{D-2} \int d^D x \sqrt{|g_D|} [f(R) + c_1 R_{AB}R^{AB} + c_2 R_{ABCD}R^{ABCD}]. \quad (56)$$

This action represents an example of the effective theory [26]. Here, c_1, c_2 are parameters of the Lagrangian, and $f(R)$ is a function of the Ricci scalar R . The Gauss–Bonnet Lagrangian

$$\mathcal{L}_{GB} = k\sqrt{-g} \left\{ R^2 - 4R_{AB}R^{AB} + R_{ABCD}R^{ABCD} \right\} \quad (57)$$

belongs to such set of models and is the appropriate starting point because of the absence of higher derivatives.

The action

$$S_{gen} = \frac{1}{2}m_D^{D-2} \int d^D x \sqrt{|g_D|} [\tilde{f}(R) + k \left\{ R^2 - 4R_{AB}R^{AB} + R_{ABCD}R^{ABCD} \right\}] \quad (58)$$

is used in the following. This action is the particular case of the action (56) provided that $\tilde{f}(R) = f(R) - kR^2$ and $c_1 = -4k, c_2 = k$. In what follows, we will consider only the quadratic function

$$f(R) = aR^2 + bR + c \quad (59)$$

($b = 1$ without the loss of generality).

We assume that both subspaces are three-dimensional maximally symmetric subspaces of positive curvature

$$ds^2 = dt^2 - e^{2\alpha(t)} m_D^{-2} [dx^2 + \sin^2(x) dy^2 + \sin^2(x) \sin^2(y) dz^2] - e^{2\beta(t)} m_D^{-2} [d\theta^2 + \sin^2(\theta) d\phi^2 + \sin^2(\theta) \sin^2(\phi) d\psi^2]. \quad (60)$$

Einstein's equations for this model are

$$\begin{aligned} & -\frac{1}{2} \tilde{f}(R) \delta_B^A + (R_B^A + \nabla^A \nabla_B - \delta_B^A \square) \tilde{f}_R + k \left[-8R^{AC}{}_{;BC} - 12R^{AC} R_{CB} \right. \\ & + 2\delta_B^A R_{CD} R^{CD} - \frac{\delta_B^A}{2} R^{CDEF} R_{CDEF} + 2R^{ACDE} R_{BCDE} + 4R^{;A}{}_{;B} \\ & \left. + 4R^{CAD}{}_{;B} R_{CD} - \frac{\delta_B^A}{2} R^2 + 2R R_B^A \right] = 0, \end{aligned} \quad (61)$$

The nontrivial system of Equation (61) is

$$\begin{aligned} & -36k \left[\dot{\alpha} \dot{\beta}^3 + 3\dot{\alpha}^2 \dot{\beta}^2 + \dot{\alpha}^3 \dot{\beta} + e^{-2\alpha} \dot{\beta} (\dot{\beta} + \dot{\alpha}) + e^{-2\beta} \dot{\alpha} (\dot{\beta} + \dot{\alpha}) + e^{-2\beta} e^{-2\alpha} \right] \\ & -3\tilde{f}_{RR} \dot{R} (\dot{\alpha} + \dot{\beta}) + 3\tilde{f}_R \left(\ddot{\alpha} + \ddot{\beta} + \dot{\alpha}^2 + \dot{\beta}^2 \right) - \frac{1}{2} \tilde{f}(R) = 0, \end{aligned} \quad (62)$$

$$\begin{aligned} & -12k \left\{ 2\ddot{\alpha} \dot{\beta} (\dot{\alpha} + \dot{\beta}) + \ddot{\beta} \left(\dot{\alpha}^2 + 4\dot{\alpha} \dot{\beta} + \dot{\beta}^2 \right) + 2\dot{\alpha}^3 \dot{\beta} + 6\dot{\alpha}^2 \dot{\beta}^2 + 6\dot{\alpha} \dot{\beta}^3 + \dot{\beta}^4 \right. \\ & \left. + e^{-2\alpha} \left[\ddot{\beta} + 2\dot{\beta}^2 \right] + e^{-2\beta} \left[2\ddot{\alpha} + \ddot{\beta} + 3\dot{\alpha}^2 + 2\dot{\alpha} \dot{\beta} + \dot{\beta}^2 \right] + e^{-2\alpha} e^{-2\beta} \right\} - \tilde{f}_{RRR} \dot{R}^2 \\ & - \tilde{f}_{RR} [\ddot{R} + \dot{R} (2\dot{\alpha} + 3\dot{\beta})] + \tilde{f}_R \left(\ddot{\alpha} + 3\dot{\alpha}^2 + 3\dot{\alpha} \dot{\beta} + 2e^{-2\alpha} \right) - \frac{1}{2} \tilde{f}(R) = 0, \end{aligned} \quad (63)$$

$$\begin{aligned} & -12k \left\{ \ddot{\alpha} \left(\dot{\alpha}^2 + 4\dot{\alpha} \dot{\beta} + \dot{\beta}^2 \right) + 2\ddot{\beta} \dot{\alpha} (\dot{\alpha} + \dot{\beta}) + \dot{\alpha}^4 + 6\dot{\alpha}^3 \dot{\beta} + 6\dot{\alpha}^2 \dot{\beta}^2 + 2\dot{\alpha} \dot{\beta}^3 \right. \\ & \left. + e^{-2\alpha} \left[\ddot{\alpha} + 2\ddot{\beta} + \dot{\alpha}^2 + 2\dot{\alpha} \dot{\beta} + 3\dot{\beta}^2 \right] + e^{-2\beta} \left[\ddot{\alpha} + 2\dot{\alpha}^2 \right] + e^{-2\alpha} e^{-2\beta} \right\} - \tilde{f}_{RRR} \dot{R}^2 \\ & - \tilde{f}_{RR} [\ddot{R} + \dot{R} (3\dot{\alpha} + 2\dot{\beta})] + \tilde{f}_R \left(\ddot{\beta} + 3\dot{\alpha} \dot{\beta} + 3\dot{\beta}^2 + 2e^{-2\beta} \right) - \frac{1}{2} \tilde{f}(R) = 0, \end{aligned} \quad (64)$$

where we have kept in mind denotations $\partial_t(\tilde{f}_R) = \tilde{f}_{RR} \dot{R}$ and $\partial_t^2(\tilde{f}_R) = \tilde{f}_{RRR} \dot{R}^2 + \tilde{f}_{RR} \ddot{R}$. The Ricci scalar is

$$R = 6 \left(\ddot{\beta} + \ddot{\alpha} + 2\dot{\beta}^2 + 3\dot{\alpha} \dot{\beta} + 2\dot{\alpha}^2 + e^{-2\beta} + e^{-2\alpha} \right). \quad (65)$$

Here, and in the following, the units $m_D = 1$ are assumed.

As in Section 3.1, it is convenient to consider the Ricci scalar $R(t)$ as the additional unknown function and interpret definition (65) as the fourth equation of the system with respect to unknown functions $\alpha(t)$, $\beta(t)$, and $R(t)$. Three equations of this system (for example, (63)–(65)) can be solved with respect to the higher derivatives $\ddot{\alpha}$, $\ddot{\beta}$, \ddot{R} . Then, substituting $\ddot{\alpha}$ and $\ddot{\beta}$ into Equation (62), we obtain the equation

$$\begin{aligned} & -36k \left[\dot{\alpha}^3 \dot{\beta} + 3\dot{\alpha}^2 \dot{\beta}^2 + \dot{\alpha} \dot{\beta}^3 + e^{-2\alpha} \dot{\beta} (\dot{\alpha} + \dot{\beta}) + e^{-2\beta} \dot{\alpha} (\dot{\alpha} + \dot{\beta}) + e^{-2\alpha} e^{-2\beta} \right] \\ & -3 (\dot{\alpha} + \dot{\beta}) \dot{R} \tilde{f}_{RR} + \left(-3\dot{\alpha}^2 - 9\dot{\alpha} \dot{\beta} - 3\dot{\beta} - 3e^{-2\alpha} - 3e^{-2\beta} + \frac{R}{2} \right) \tilde{f}_R - \frac{\tilde{f}}{2} = 0, \end{aligned} \quad (66)$$

The standard initial conditions are not independent due to Equation (66). The latter must be used to obtain a relation between these initial data.

The free parameters $a \sim k \sim m_D^{-2}$, $c \sim m_D^2$ are not related to the observational values because of the strong and uncontrolled contribution of the quantum corrections at sub-Planckian energies.

An example of numerical solution to system (62)–(64) is represented in Figure 4.

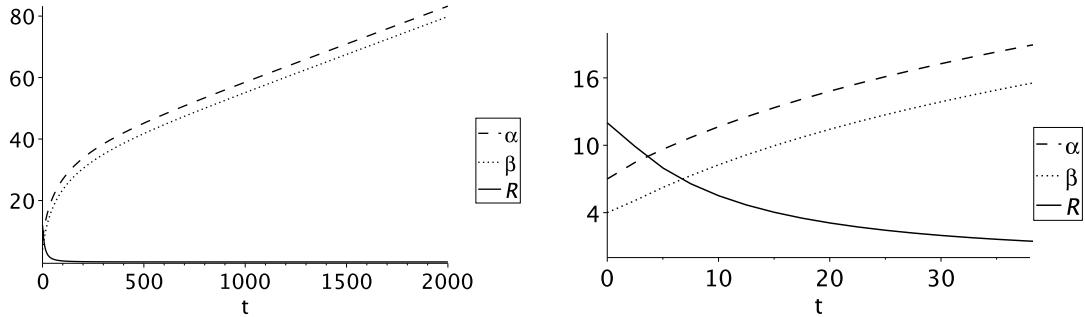


Figure 4. Numerical solution to the system of Equations (63)–(65) for initial conditions $\alpha(0) = 7$, $\dot{\alpha}(0) = 1$, $\beta(0) = 4$, $\dot{\beta}(0) = 0$, $\dot{R}(0) = 0$. The initial condition $R(0) \simeq 11.999$ is found from Equation (66). The Lagrangian parameters are $a = 200$, $c = -0.001$, $k = 500$.

The choice of another set of physical parameters can change the picture. Sub-spaces grow at different rates as is represented in Figures 5 and 6.

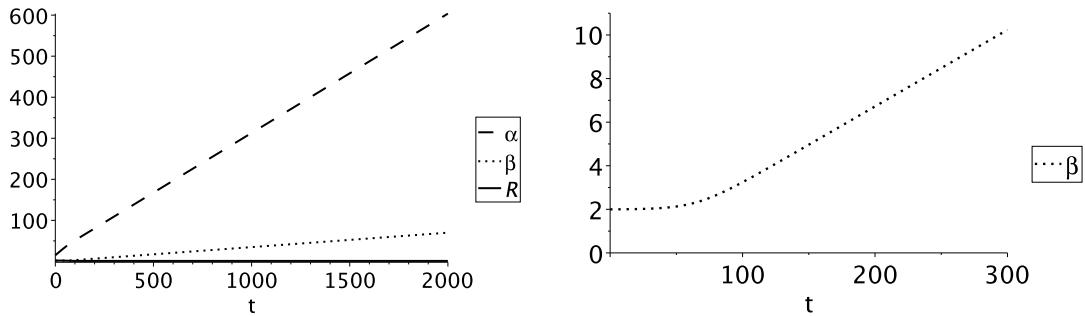


Figure 5. Numerical solution to the system of Equations (63)–(65) for initial conditions $\alpha(0) = 15$, $\dot{\alpha}(0) \simeq 0.404667$, $\beta(0) = 2$, $\dot{\beta}(0) = 0$, $\dot{R}(0) = 0$. $R(0) \simeq 2.09126$ is found from Equation (66). The Lagrangian parameters are $a = -2.77$, $c = -0.49$, $k = -2.98$.

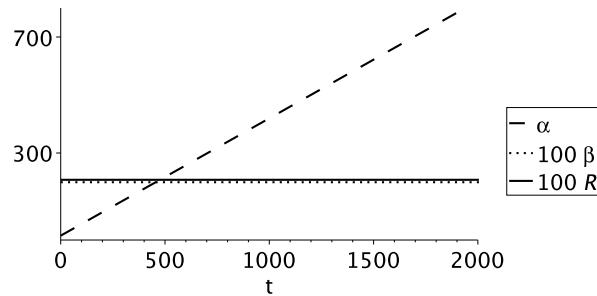


Figure 6. Numerical solution to the system of Equations (63)–(65) for initial conditions $\alpha(0) = 15$, $\dot{\alpha}(0) \simeq 0.40467$, $\beta(0) = b_c \simeq 1.99303$, $\dot{\beta}(0) = 0$, $\dot{R}(0) = 0$. $R(0) \simeq 2.0765$ is found from Equation (66). For the found numerical solution, $a = -2.77$, $c = -0.49$, $k = -2.98$.

4. Approximate Method

The gravity with higher derivatives provides us with new abilities in understanding the role of metric in the observed world. The price is that the analysis becomes much more complicated.

The attraction of extra dimensions aggravates the situation. Fortunately, a small parameter arises naturally, provided that the extra space is small and compact. Let us accept for estimation that the average Ricci scalar R_n of the extra space relates to its size r_n as $R_n \sim 1/r_n^2$. This means that R_n is in many orders of magnitude larger than the 4-dim Ricci scalar.

As a result, small parameter

$$\epsilon \equiv R_4/R_n \ll 1 \quad (67)$$

appears that strongly facilitate an analysis. Below, we follow the method developed in [27]

4.1. Basic Idea

Consider the gravity with higher derivatives (1). The metric is assumed to be the direct product $M_4 \times V_n$ of the 4-dim space M_4 and n -dim compact space V_n

$$ds^2 = g_{6,AB}dz^A dz^B = g_{4,\mu\nu}(x)dx^\mu dx^\nu + g_{n,ab}(y)dy^a dy^b. \quad (68)$$

Here, $g_{4,\mu\nu}$ is a metric of the manifolds M_4 and $g_{n,ab}(y)$ is a metric of the manifolds V_n . x and y are the coordinates of the subspaces M_4 and V_n , respectively. We will refer to 4-dim space M_4 and n -dim compact space V_n as the main space-time and an extra space, respectively. The metric has the signature (+ - - - ...), the Greek indexes $\mu, \nu = 0, 1, 2, 3$ refer to 4-dimensional coordinates. Latin indexes run over $a, b = 4, 5, \dots$

According to (68), the Ricci scalar represents a simple sum of the Ricci scalar of the main space and the Ricci scalar of extra space

$$R = R_4 + R_n. \quad (69)$$

In this section, the extra space is assumed to be maximally symmetric so that its Ricci scalar $R_n = \text{const.}$

Using inequality (67) the Taylor expansion of $f(R)$ in Equation (1) gives

$$\begin{aligned} S &= \frac{m_D^{D-2}}{2} \int d^4x d^n y \sqrt{|g_4(x)|} \sqrt{|g_n(y)|} f(R_4 + R_n) \\ &\simeq \frac{m_D^{D-2}}{2} \int d^4x d^n y \sqrt{|g_4(x)|} \sqrt{|g_n(y)|} [R_4(x)f'(R_n) + f(R_n)] \end{aligned} \quad (70)$$

The prime denotes derivation of functions on its argument. Thus, $f'(R)$ stands for df/dR in the formula written above. Comparison of the second line in expression (70) with the Einstein–Hilbert action

$$S_{EH} = \frac{M_P^2}{2} \int d^4x \sqrt{|g(x)|} (R - 2\Lambda) \quad (71)$$

gives the expression

$$M_P^2 = m_D^{D-2} v_n f'(R_n) \quad (72)$$

for the Planck mass. Here, v_n is the volume of the extra space. The term

$$\Lambda \equiv -\frac{m_D^{D-2}}{2M_{Pl}^2} v_n f(R_n) \quad (73)$$

represents the cosmological Λ term. Both the Planck mass and the Λ term depend on a function $f(R)$. Notice that, according to (72), the Planck mass could be smaller than D -dim Planck mass, $M_{Pl} < m_D$ for specific functions f that could lead to nontrivial consequences.

4.2. Extension of the Model: Low Energies

The quantum fluctuations of metric produce all possible terms that are invariant under the coordinate transformations [26,28]. We extend our study to effective action in the form (56)

$$S_{gen} = \frac{1}{2} m_D^{D-2} \int d^D x \sqrt{g_D} [f(R) + c_1 R_{AB} R^{AB} + c_2 R_{ABCD} R^{ABCD}]. \quad (74)$$

Another point is that the extra space metric depends on all coordinates, not only those describing extra dimensions. Therefore, the small parameter method should be expanded for this more general case.

In this section, we use small parameter (67) and the conformal transformations analogous to conformal transformations (4) to clarify the classical behavior of system acting in D dimensions.

Here, we consider a $D = 4 + n$ - dimensional manifold \mathbb{M} , having the simplest geometric structure of a direct product, $\mathbb{M} = \mathbb{M}_4 \times \mathbb{M}_n$, with the metric

$$ds^2 = dt^2 - e^{\alpha(x)} (dr^2 + r^2(d\theta^2 + \sin^2(\theta)d\varphi^2)) - e^{2\beta(x)} d\Omega_n^2. \quad (75)$$

It is assumed that the extra space is n -dimensional maximally symmetrical manifold with positive curvature.

The size of extra dimensions is supposed to be small compared to the size of our 4-dim space so that inequality (67) holds and we may follow the method elaborated in [27,29]. According to (75), the Ricci scalar is

$$R = R_4 + R_n + P_k; \quad P_k = +n(n+1)(\partial\beta)^2 + 2n\Box\beta + 6n\partial_\mu\alpha\partial^\mu\beta. \quad (76)$$

The additional inequality

$$P_k \ll R_n \quad (77)$$

means that fluctuations of the 4-dim metric coefficient $\beta(x)$ are smooth. More specifically,

$$|\partial_\mu g_{AB}| \sim \epsilon |\partial_a g_{AB}|, \quad \epsilon \ll 1. \quad (78)$$

Using Formulas (68)–(77), we can perform the Taylor decomposition of the function $f(R)$ to transform the action as

$$S = \frac{1}{2} v_n \int d^{d_0} x \sqrt{-g_0} e^{d_2 \beta_n} [f'(R_n) R_4 + f'(R_n) P_k + f(R_n) + c_1 R_{AB} R^{AB} + c_2 R_{ABCD} R^{ABCD}], \quad (79)$$

$$R_n = \phi = n(n-1)e^{-2\beta(x)}, \quad (80)$$

$$R_{AB} R^{AB} = \frac{(n-1)^2}{n} e^{-4\beta} + 2n(n-1)e^{-2\beta} (\Box\beta_2 + n(\partial\beta)^2 + 4\partial_\mu\alpha\partial^\mu\beta) + O(\epsilon^4),$$

$$R_{ABCD} R^{ABCD} = 2\frac{n-1}{n} e^{-4\beta} + 4n(n-1)e^{-2\beta} (\partial\beta)^2 + O(\epsilon^4).$$

The action of the form (79) is written in the Jordan frame. We consider this frame as a "physical" one which gives us the Planck mass, in particular

$$M_P^2 = v_n f'(\phi_m); \quad v_n = \frac{2\pi^{\frac{n+1}{2}}}{\Gamma(\frac{n+1}{2})} e^{n\beta_m}. \quad (81)$$

Here, ϕ_m delivers a minimum of $V_E(\phi)$ (see definition (85) below).

It is more familiar to work in the Einstein frame. To this end, we have to perform the conformal transformation (4)

$$g_{ab} \rightarrow g_{ab}^{(E)} = e^{n\beta} |f'(\phi)| g_{ab}, \quad \phi \equiv R_n = n(n-1)e^{-2\beta(x)} \quad (82)$$

of the metric describing the subspace M_4 . This leads to the action in the Einstein frame in form

$$S_{low} = \frac{1}{2} v_n \int d^4x \sqrt{g_4} \operatorname{sign}(f') [R_4 + K(\phi)(\partial\phi)^2 - 2V(\phi)], \quad (83)$$

$$K(\phi) = \frac{1}{4\phi^2} \left[6\phi^2 (f''/f')^2 - 2n\phi(f''/f') + \frac{1}{2}n(n+2) \right] + \frac{c_1 + c_2}{f'\phi}, \quad (84)$$

$$V(\phi) = -\frac{\operatorname{sign}(f')}{2f'^2} \left[\frac{|\phi|}{n(n-1)} \right]^{n/2} \left[f(\phi) + \frac{c_V}{n} \phi^2 \right], \quad c_V = c_1 + \frac{2c_2}{(n-1)} \quad (85)$$

representing specific Lagrangian of the scalar-tensor gravity [27]. Here, $D = 4 + n$ and the physical meaning of the effective scalar field ϕ is the Ricci scalar of the extra space.

An important remark is necessary. The action (79) describes the field evolution at high energies in the Jordan frame. When the scalar field is settled in its minimum, we should express the 4-dim Planck mass according to (81). Simultaneously, the scalar field is evolving during inflation, and it is worth using the Einstein frame to facilitate analysis. In this case, we should consider

$$m_4 \equiv \sqrt{v_n} \quad (86)$$

as the effective Planck mass during the inflation in the Einstein frame.

Let us impose restrictions that follow from the observational data at low energies. In this case, observable value of the cosmological constant is extremely small and we neglect it. We also assume that the field ϕ is in its stationary state. Thus, necessary conditions are as follows:

$$V(\phi_m) = 0; \quad V'(\phi_m) = 0. \quad (87)$$

The inequalities

$$\phi_m > 0, \quad f'(\phi_m) > 0, \quad K(\phi_m) > 0. \quad V''(\phi_m) = m^2 > 0 \quad (88)$$

are necessary to consider the field ϕ as the scalar field with the standard properties. The function $f(R)$ should be specified to make specific predictions. It is chosen in the form

$$f(R) = aR^2 + bR + c. \quad (89)$$

One can easily solve algebraic Equation (87) with respect to

$$\phi_m = -\frac{b}{2(a + c_V/n)} \quad (90)$$

and

$$c = \frac{b^2}{4(a + c_V/n)}. \quad (91)$$

Our 4-dimensional space-time is surely not Minkowskian so that the relation (91) holds approximately.

Let's consider inequalities (88) in more detail. The first inequality in (88) leads to

$$-\frac{b}{2(a + c_V/n)} > 0. \quad (92)$$

The second inequality in (88) gives

$$f'(\phi_m) > 0 \rightarrow \frac{bc_V/n}{(a + c_V/n)} > 0. \quad \text{or} \quad c_V < 0 \quad (93)$$

The third inequality in (88) gives the inequality

$$\left[(12a^2 + 4ac_V + c_V^2)n + 2c_V^2 - 4c_V(c_1 + c_2) \right] > 0, \quad (94)$$

and the fourth equality in (88) leads to

$$V''(\phi_m) = -\frac{bn^2}{c_V^2} \left(\frac{a + c_V/n}{b} \right)^3 \left[-\frac{b}{2(a + c_V/n)n(n-1)} \right]^{n/2} \equiv m^2 > 0 \quad \text{i.e.} \quad b > 0. \quad (95)$$

As the result, the parameters of action must satisfy the conditions

$$b > 0, c_V < 0, a + c_V/n < 0. \quad (96)$$

The presence of a small parameter permits solving two problems. The consideration is reduced to the standard Einstein gravity + scalar field, and four dimensions appear naturally because the integration of the extra coordinate is trivial. The potential of the scalar field is promising from the point of view appropriate inflationary scenario. We show below how to elaborate the inflationary model.

4.3. Extension of the Model: Moderate Energies

The study above indicates that some limits on the Lagrangian parameter values can be derived in this approach's framework. Nevertheless, freedom in the choice of the parameter values remains. This freedom that is used below can be used to obtain e.g., appropriate inflationary models, see [30,31] for details.

First of all, we have to specify our action (83) by definition of the function $f(R)$ (89). The final form of the action is

$$S = \frac{m_4^2}{2} \int d^4x \sqrt{-g_4} \text{sign}(2a\phi + b) \left\{ R + K(\phi)\phi_{;\rho}\phi^{\rho} - 2V(\phi) \right\}, \quad (97)$$

where

$$m_4 = \sqrt{V_n} = \sqrt{\frac{2\pi^{\frac{n+1}{2}}}{\Gamma(\frac{n+1}{2})}}, \quad m_D = 1, \quad (98)$$

and

$$\begin{aligned} K(\phi) &= \frac{1}{\phi^2(2a\phi + b)^2} \left\{ \left[(6 - n + \frac{n^2}{2})a^2 + 2(c_1 + c_2)a \right] \phi^2 \right. \\ &\quad \left. + \left[\frac{n^2}{2}ab + (c_1 + c_2)b \right] \phi + \frac{n(n+2)}{8}b^2 \right\}, \end{aligned} \quad (99)$$

$$V(\phi) = -\frac{\text{sign}(2a\phi + b)}{2(2a\phi + b)^2} \left[\frac{\phi}{n(n-1)} \right]^{n/2} \left\{ \left(a + \frac{c_V}{n} \right) \phi^2 + b\phi + c \right\}, \quad (100)$$

and

$$c_V = c_1 + 2 \frac{c_2}{n-1}. \quad (101)$$

The kinetic factor $K(\phi)$ and the potential $V(\phi)$ have a complex form depending on several parameters. They are represented in Figure 7 for the parameter values

$$n = 2, b = 1, a = -2, c_V = -8, c_K = 15000, \quad (102)$$

$$\left(c_V = c_1 + 2 \frac{c_2}{n-1}, c_K = c_1 + c_2. \right)$$

The parameter "c" can be obtained from expression (91). Restrictions (88)–(95) are also taken into account.

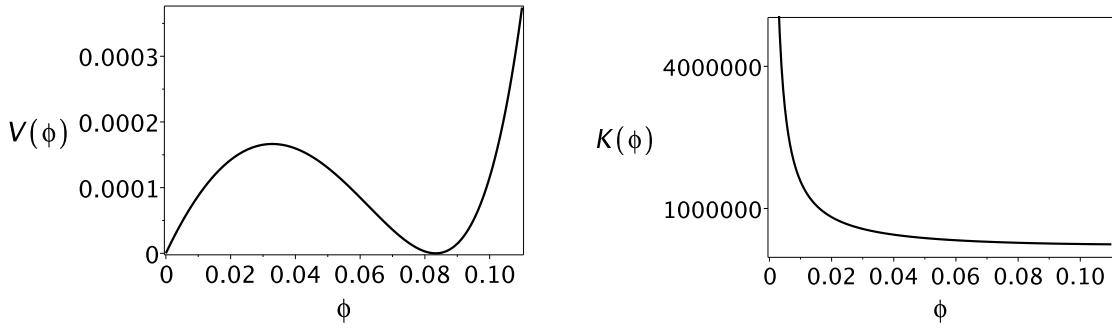


Figure 7. The form of the potential (left) and kinetic term (right) for the parameters $n = 2, b = 1, a = -2, c_V = -8, c_K = 15000$. The potential minimum is in the point $\phi_m \simeq 0.083, m_D = 1$.

Finally, we must check inequality (67) (written in the Jordan frame) to be sure in the self-consistency of our approach. The n-dim scalar Ricci is not transformed under conformal transformations (82) so that $R_2 = \phi$. Let us estimate the 4-dim part of the Ricci scalar R_4 keeping in mind the slow motion regime which is inherent for the inflationary period. In this case, $R_4^{(E)} = 12H^2 \simeq 12 \cdot 8\pi V(\phi)/3M_{Pl}^2$ in the Einstein frame. A relation to the Jordan frame may be found in (4), (5), and (82). Finally,

$$\epsilon \equiv R_4^{(J)}/R_n \sim 100f'(\phi)V(\phi)/\phi^2. \quad (103)$$

Our approximation (67) holds if the field ϕ is varied near the potential minimum, $\phi = \phi_m$, in the region where the potential is limited from above

$$V(\phi) \ll \frac{\phi_m^2}{100f'(\phi_m)} \sim 10^{-4} \quad (104)$$

Here, $\phi_m = 0.083$ in the units $m_D = 1$ according to the figure above. As we will see just below, $m_D \sim 0.1 M_{Pl}$ so that the limitation (104) is not very restricted: $V \ll 10^{-8} M_{Pl}^4$.

In the main text above, we express all quantities in units $m_D = 1$ with the effective Planck mass m_4 defined by (86). Finally, when the scalar field ϕ has been settled in the minimum of its potential $V(\phi)$, one should restore more physical units valid for the Jordan frame, i.e., the Planck units using the relation (81). For chosen parameter values (102), the relation

$$M_{Pl} = \sqrt{V_n e^{n\beta_m} f'(\phi_m)} m_D \quad (105)$$

can be used to obtain the value of the D-dimensional Planck mass. For two-dimensional extra space ($n = 2$, $V_2 = 4\pi$),

$$M_{Pl} = \sqrt{V_2 e^{2\beta_m} f'(\phi_m)} m_D = \sqrt{8\pi(2a + \frac{1}{\phi_m})} m_D \sim 10m_D, \quad (106)$$

which means that the D-dim Planck mass m_D is in the order of magnitude smaller than the Planck mass in the Jordan frame.

One can see that the presence of a small parameter strongly facilitates the analysis and could lead to promising results, even if the initial system is quite complicated. Indeed, it is hard even to guess that action (74) could adequately describe the inflationary stage. On the other side, the energy density at the moderate energies (inflation) is not small, so that one must check the smallness of the parameter value (67).

5. Method of Trial Functions

This method is applied if a system in question is too complicated, see, e.g., [32,33]. The mathematically correct way to deal with gravitational systems is as follows. One should type equations of motion for a metric of the most general form, and solves it for desired initial and boundary conditions. The freedom in the coordinate choice facilitates the analysis, but the system often remains too complicated to be solved. The problem is usually solved by choosing a limited set of metrics that is substituted into an action. Classical equations are obtained by variation of the metric belonging to the chosen set. The well-known example is the minisuperspace model of Universe creation. The method of trial functions is one of such a sort. Its essence is to choose an appropriate set of metrics—some functions depending on parameters. The action appears to be dependent on the set of unknown parameters. The classical system of equations is reduced to an algebraic system for these parameters.

Let us illustrate it by the specific solution that non trivially connects two sub-spaces. Consider a manifold M with topology $T \times M_1 \times M_2 \times M_3$, where M_1 is one-dimensional, infinite space, and M_2, M_3 are two-dimensional spheres. We study the pure gravitational field action in the form (74) with the metric

$$ds^2 = A(u)dt^2 - A(u)^{-1}du^2 - e^{2\beta_1(u)}d\Omega_1^2 - e^{2\beta_2(u)}d\Omega_2^2. \quad (107)$$

Here, $A(u)$, $\beta_1(u)$, and $\beta_2(u)$ are members of the limited set of metrics depending on the Schwarzschild radial coordinate u , $-\infty < u < \infty$. The action contains invariants depending on these functions. For example, the Ricci scalar has the form (see [34,35] for details)

$$\begin{aligned} R = & 2e^{-2\beta_1} + 2e^{-2\beta_2} - A'' - 4A'(\beta'_1 + \beta'_2) \\ & - 2A(3\beta_1'^2 + 3\beta_2'^2 + 4\beta'_1\beta'_2 + 2\beta_1'' + 2\beta_2''), \end{aligned} \quad (108)$$

with prime denoting differentiation with respect to u .

Let us study the metric that represents the transition between the domain with (large M_2 /small M_1) subspaces and the domain with subspaces (large M_1 /small M_2) [34] with the Minkowski metric at the asymptotes:

$$A(u \rightarrow \pm\infty) \rightarrow 1, \quad (109)$$

and

$$\begin{aligned} \beta_1(u \rightarrow +\infty) & \rightarrow \ln u, & \beta_1(u \rightarrow -\infty) & \rightarrow \ln r_0, \\ \beta_2(u \rightarrow -\infty) & \rightarrow \ln u, & \beta_2(u \rightarrow +\infty) & \rightarrow \ln r_0. \end{aligned} \quad (110)$$

Here, $r_0 = e^{\beta_c}$ is the radius of extra space at $u \rightarrow \pm\infty$. The value of $r_0 = 1/\sqrt{-c}$ is connected with the physical parameter c according to Formulas (80)–(91).

For the numerical simulations, we use the Ritz method which means that the functions $A(u), \beta_1(u), \beta_2(u)$ in (107) are approximated by trial functions that are chosen in the form

$$A(u) = 1 - \frac{\xi_2}{\sqrt{\xi_1^2 + u^2}}, \quad (111)$$

$$e^{\beta_1(u)} = r_0 + \frac{1}{2} \left(u + \sqrt[4]{\xi_3^4 + u^4} \right),$$

$$e^{\beta_2(u)} = r_0 - \frac{1}{2} \left(u - \sqrt[4]{\xi_3^4 + u^4} \right),$$

keeping in mind conditions (109), (110). According to [35], the parameters ξ_1, ξ_2, ξ_3 should satisfy equation

$$\left(\frac{2\xi_2}{c} + \xi_1^2 \xi_2 + 3\sqrt{-c} \xi_3^4 \right) (1 - 4c^2) + 3c_1(-c)^{3/2} \xi_3^4 = 0. \quad (112)$$

In what follows, we consider ξ_1, ξ_3 as independent values, and ξ_2 as their function. Parameters ξ_1, ξ_2, ξ_3 are to be defined by the action minimization.

Now, the action $S(\xi_1, \xi_3)$ appears to be a function of two variables after the substitution of trial functions (111) into action (74). Classical solutions should satisfy equations

$$\frac{\delta S}{\delta g_{ab}} = 0 \quad (113)$$

or, according to the Ritz method, [36]

$$\frac{\partial S}{\partial \xi_1} = 0, \quad \frac{\partial S}{\partial \xi_3} = 0. \quad (114)$$

One of the ways to solve this system is to find a minimum of the auxiliary function

$$\Omega(\xi_1, \xi_2(\xi_1, \xi_3), \xi_3) = \left(\frac{\partial S}{\partial \xi_1} \right)^2 + \left(\frac{\partial S}{\partial \xi_3} \right)^2. \quad (115)$$

The minimization procedure for $\Omega(\xi_1, \xi_2(\xi_1, \xi_3), \xi_3)$ gives the minimum at $\xi_1^* = 9.96, \xi_2^* = 9.57, \xi_3^* = 1.85$, see Figure 8. The minimum is very profound so that the trial functions, see Figure 9, are chosen properly.

For an external observer, the funnel looks like a microscopic object with the mass of the Planck scale's order.

The method of trial functions (the Ritz method) is a useful tool to study complicated systems provided that the boundary conditions are known.

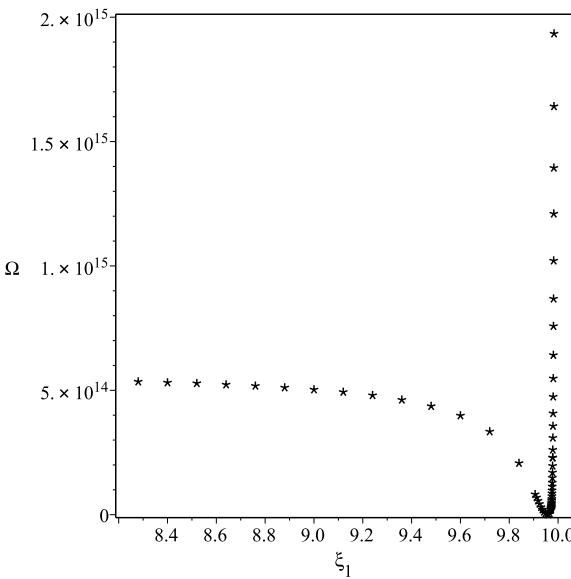


Figure 8. Auxiliary function Ω vs. the minimization parameter ξ_1 for $\xi_2^* = 9.57, \xi_3^* = 1.85$ and $f(R)$ -parameters $a = -2, b = 1, c = -0.02$. The minimum of Ω corresponds to $\xi_1^* = 9.96$. $\Omega(\xi_1^* = 9.96, \xi_3^* = 1.85) = 5.3 \times 10^{11}$.

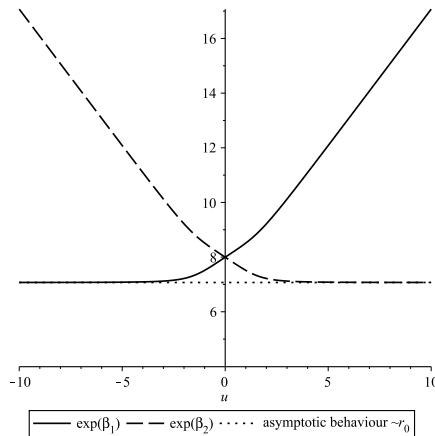


Figure 9. Radii of two-dimensional subspaces vs. the Schwarzschild radial coordinate u for parameter values $a = -2, b = 1, c = -0.02, \xi_3 = 1.85$.

6. Conclusions

In this review, we discussed the working methods that help to cope with the mathematical difficulties of gravity with higher derivatives. All methods are supplied by examples that help to reveal the positive and negative aspects of each approach.

The method based on the conformal transformation strongly facilitates analysis in some cases, but it is mostly limited by $f(R)$ models. In addition, caution in the application of this method is necessary if the quantum effects are essential.

The direct solution of the system of differential equations followed from an action minimization is a complicated problem. In addition, the progress is possible if these equations are of the second order in time derivatives. The latter is not obligatorily true for models containing invariants other than the Ricci scalar.

If the system contains a small parameter, this usually helps to obtain results. The ratio of the Ricci scalars of extra dimensions and those measured in the present Universe can be used in many models containing the extra space. It often helps to reduce a primary D-dim action with higher derivatives to

the 4-dimensional action with a scalar field. The smallness of such ratio (67) should be controlled at high energies intentionally.

The trial functions method is quite universal, but the accuracy of results is not evident, and efforts should be applied to clarify the question.

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