

METHOD OF EXTERIOR CENTERS WITH USE OF ADDUCED GRADIENT FOR THE PROBLEM OF NONLINEAR PROGRAMMING

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Introduction

We consider the problem

$$\min\{f_0(x), x \in \Omega\}, \quad \Omega = \{x \in E^n \mid f_j(x) \leq 0, j \in J\}, \quad (1)$$

where E^n is an n -dimensional Euclidean space, J is a finite set of indices, the functions $f_j(x)$ are from $C^{(2)}(E^n)$, $j \in J \cup \{0\}$.

By a solution of problem (1) we shall mean a point x_* satisfying necessary conditions of a minimum of first order: numbers $\lambda_*^j \geq 0$, $j \in J$, exist such that

$$f'_0(x_*) + \sum_{j \in J} \lambda_*^j f'_j(x_*) = 0, \quad \lambda_*^j f_j(x_*) = 0, \quad j \in J, \quad x \in \Omega. \quad (2)$$

In [1], [2], a united scheme of construction and investigation of method for solving problem (1) was offered, based on the use of an "adduced" direction in the capacity of the motion direction at a current iteration point and application of various penalty functions for the choice of step's length.

Within the framework of the united scheme both known and new methods of exact (see [1]) and differentiable penalty functions (see [3]) were realized, as well as methods of possible directions (see [2]) and the modified Lagrange functions (see [4]), method of centers and barrier functions (see [5]).

In the present article we suggest to use in the capacity of the payoff function the exterior distance function (see [6], p. 84)

$$\Phi_\beta(x) = ((f_0(x) - \beta)^+)^2 + \sum_{j \in J} (f_j^+(x))^2, \quad y^+ = \max\{0, y\}, \quad (3)$$

realizing within the framework of the united scheme both the known and new methods of centers. Here β is penalty parameter. Let us note that function (3) was applied earlier by many authors in the methods of loaded functions.

1. Method of exterior center

The set

$$J_0(x) = \{j \in J \mid f_j(x) \geq 0\}$$

will be called the index set of "working" constraints.

Let the following conditions be fulfilled.

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