

STRONGLY RESONANCE ELLIPTIC VARIATIONAL INEQUALITIES WITH DISCONTINUOUS NONLINEARITIES

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1. Problem statement and the main result

Let Ω be a bounded area in \mathbf{R}^n , $n \geq 2$, whose boundary Γ belongs to the class $\mathbf{C}_{2,\alpha}$, $0 < \alpha \leq 1$ ([1], p. 23), $K = \{v \in \overset{\circ}{\mathbf{W}}_2^1(\Omega) \mid v(x) \geq \psi(x) \text{ almost everywhere on } \Omega\}$, where $\psi \in \mathbf{C}_2(\overline{\Omega})$, $\psi|_{\Gamma} \leq 0$.

The problem implies finding a function $u \in K$ which satisfies the inequality

$$\sum_{i,j=1}^n \int_{\Omega} a_{ij}(x) u_{x_i} (v - u)_{x_j} dx + \int_{\Omega} (a_0(x) - \lambda_0) u(x) (v - u)(x) dx + \int_{\Omega} g(x, u) (v - u)(x) dx \geq 0 \quad \forall v \in K. \quad (1)$$

Here $Lu(x) \equiv - \sum_{i,j=1}^n (a_{ij}(x) u_{x_i})_{x_j} + a_0(x) u(x)$ is a uniformly elliptic differential operator, $a_{ij} \in \mathbf{C}_{1,\alpha}(\overline{\Omega})$, $a_0 \in \mathbf{C}_{0,\alpha}(\overline{\Omega})$ and $a_0(x) \geq 0$ on Ω , λ_0 is the minimal eigenvalue of the operator L with the boundary condition $u|_{\Gamma} = 0$. The function $g : D \rightarrow \mathbf{R}$ ($D = \{(x, \xi) \in \Omega \times \mathbf{R} \mid x \in \Omega \text{ and } \xi \geq \psi(x)\}$) is superimposedly measurable, i. e., for any Lebesgue measurable function $u(x)$ on Ω with values $u(x) \geq \psi(x)$ the function $g(x, u(x))$ is Lebesgue measurable on Ω . In addition, we assume that for almost all $x \in \Omega$ the function $g(x, \cdot)$ has on $[\psi(x), +\infty)$ only discontinuities of the first kind and it is continuous for $\xi = \psi(x)$, $g(x, \xi) \in [g_-(x, \xi), g_+(x, \xi)]$ for any $\xi \in [\psi(x), +\infty)$, $g_-(x, \xi) = \liminf_{s \rightarrow \xi} g(x, s)$, $g_+(x, \xi) = \limsup_{s \rightarrow \xi} g(x, s)$.

Definition 1. The nonlinearity $g : D \rightarrow \mathbf{R}$ with respect to the linear differential operator $Bu = Lu - \lambda_0 u$ satisfies *A1-condition* if there exists at most a denumerable family of surfaces $\{S_i, i \in I\}$, $S_i = \{(x, \xi) \in D \mid \xi = \psi_i(x)\}$, $\psi_i \in \mathbf{W}_{1,\text{loc}}^2(\Omega)$, such that for almost all $x \in \Omega$ the inequality $g_+(x, \xi) \neq g_-(x, \xi)$ implies the existence of $i \in I$, for which $(x, \xi) \in S_i$ and $(B\psi_i(x) + g_-(x, \psi_i(x)))(B\psi_i(x) + g_+(x, \psi_i(x))) > 0$, or $B\psi_i(x) + g(x, \psi_i(x)) = 0$.

Noncoercive variational inequalities with discontinuous nonlinearities were investigated by many mathematicians. Mention the paper [2] which contains a number of relevant references. A new investigation method for such problems is proposed in this paper. Elliptic variational inequalities with discontinuous nonlinearities were investigated by one of the authors by the variational method in [3], [4] and by the method of monotone operators in [5]. However, with reference to inequalities with differential operators in the latter three papers, the order $2m$ of the differential operator is assumed to exceed the dimension of the space variable and so the differential operators of the second order are excluded. In [6], a problem with an obstacle is defined as an elliptic boundary value problem with discontinuous nonlinearity. This statement is equivalent to a variational inequality.